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About Tronhelicopters

The company Tronhelicopters was founded 2019 in Switzerland by Dario Neuenschader, Ricky Yin and Joachim Etter. (EMT team)

About us:

Dario Neuenschwander.

Dario has long been known in the RC helicopter scene for many years.

He was heavy involved in the designs of the Protos Helicopters series and the development of the famous MSH Brain FBL unit. Dario also did R@D work for SpinBlades where he is a longtime Factory Pilot.

In 2017 Dario took a break from RC Helicopters to get involved to FPV racing. He did well and took the official FPV-FAI world champion title in 2017.

Joachim Etter

Known for his business ideas and his ability to make products a success in combination with his designs. Before that, he was closely associated with various manufacturers, for whom he did designs and business consultancy. Joachim was also the key founder, designer and builder of the xnovamotors brand.

Ricky Yin

Ricky is deeply involved in the manufacture, development and production of rc model helicopters for a very long time.

That goes back to the beginnings of Synergy Helicopters, which he took over in 2010 after Stephen Fan passed away.



Features.



- Supersonic canopy mounts included in the kit. (front and backside)
- New state of the art unique and compact belt tensioner.
- Herringbone split CNC main gear and motor pinion for super quiet and efficient performance.
- New paint scheme on high visibility canopy for perfect orientation in flight. (2 options available)
- Semi fusion lower frame and tail fin for awesome look and visibility.
- Dry weight= (2190) grams without blades and electronics.
- 12mm hollow main shaft.
- 10mm feathering shaft.
- Real full carbon mainframe.
- Motor mounting features a bearing block supported pinion, reducing overall wear on the power system and drive train.
- Compatible with a wide range of motor sizes, 4030, 4035, 4525, 4530, 4535 (6mm shaft required min. length 20mm and 520 560kv.
- 16 T motor pinion included in the kit. (6mm bore diameter)
- Octa boom design with oval side shapes.
- Perfectly thought-out servo layout in conjunction with the FBL system and ESC.
- Easy cable routing with various options to ensure a clean setup. Modern, sporty and functional design.
- Wide battery compartment with quick lock and release system.



safety notice

Operate the helicopter in open areas with no people nearby. Follow your countries air regulation rules.

You may need to join a local club and become a member before you can fly the model.

Do NOT operate the helicopter in the following places and situations (or else you risk severe accidents)

In places where children gather or people pass through in residential areas and parks, indoors and in limited space in windy weather or when there is rain, snow, fog or other precipitation. If you do not observe these instructions you may be held liable for personal injury or property damage!

Always check the R/C system prior to operating your helicopter.

Keep in mind that other people around you might also be operating a R/C model. Never use a frequency which someone else is using at the same time. Radio signals will be mixed and you will lose control of your model. If the model shows irregular behavior, bring the model to a halt immediately and disconnect the batteries. Investigate the reason and fix the problem. Do not operate the model again as long as the problem is not solved, as this may lead to further trouble and unforeseen accidents. In order to prevent accidents and personal injury, be sure to observe the following: Before flying the helicopter, ensure that all screws are tightened. A single loose screw may cause a major accident.

Replace all broken or defective parts with new ones, as damaged parts lead to crashes. Never approach a spinning rotor. Keep at least 5 meters/yards away from a spinning rotor blades. Do not touch the motor immediately after use. It may be hot enough to cause burns. Perform all necessary maintenance.

PRIOR TO ADJUSTING AND OPERATING YOUR MODEL, OBSERVE THE FOLLOWING

Operate the helicopter only outdoors and out of people's reach as the main rotor operates at high rpm!

Note that a badly assembled or improperly adjusted helicopter is a safety hazard! In the beginning, novice R/C helicopter pilots should always be assisted by an experienced pilot.

SAFETY FIRST! ALWAYS.



Safety notice

CAUTION:

This radio controlled helicopter is not a toy.

The product is not suitable for children under 14 years of age.

SAFETY PRECAUTIONS:

This kit includes some preassembled components. Please check for any loose screws and tighten them before you proceed with assembly. Use loctite where required as shown in this manual!

You are responsible for assembly, safe operation, maintenance, inspection and adjustment of the model.

Before beginning assembly, please read these instructions thoroughly. Check all parts. If you find any defective or missing parts, contact your local dealer.

For the USA market, The Academy of Model Aeronautics (AMA) is a national organization representing modelers in the United States. Please refer to the National Model Aircraft safety code from Academy of Model Aeronautics.



Tools required

UHU Plus (C)	2 component epoxy		
245 ©	Loctite 243 / medium strength		
LEGISATION DE LEGIS D	Grease		
TAHLYA	2x 7mm Wrenches for tail shaft nut		
	Hex screwdriver 1.5mm/2mm/2.5mm/4m- m/5mm		
	TR701-518 Pair of customized nut wrench for tail shaft assembly. Optionally available at your Dealer.		
	SPRAG GREASE (SUCH AS ISOFLEX LDS18 Special A)		



Electronics required

	3x full size servo for swashplate		
Primary Primary	1 full size servo for tail		
	BL motor. 4030-4535 /500-560KV		
They HOBBYWING ***	ESC 6S-12S 112A-205A		
CH3	FBL device and receiver with 6 channel transmitter.		

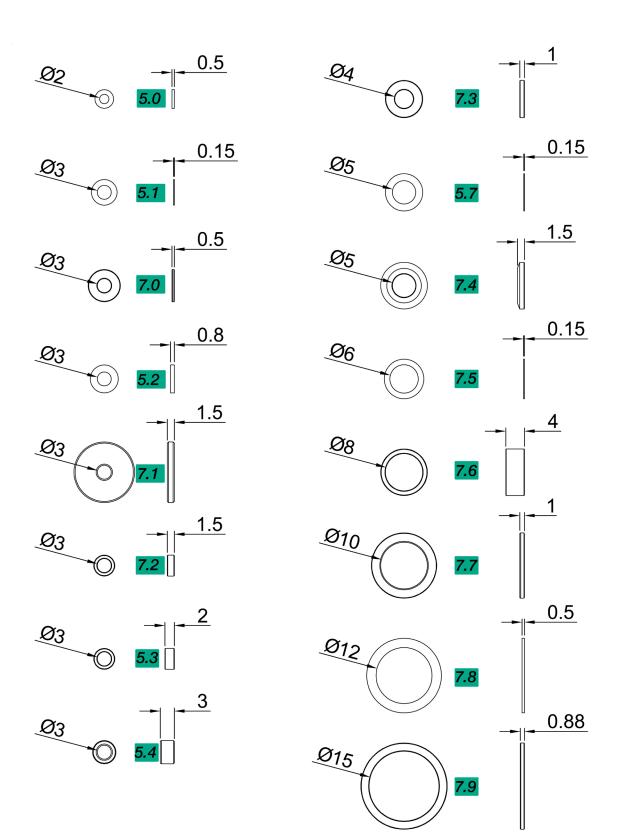


Screws and nuts

1.0	M2*4mm		2.5 M3*18mm
1.1	M2*6mm		2.6 M3*25mm
1.2	M2*16mm		2.7 M3*40mm
1.3	M2.5*6mm		2.8 M4*10mm
1.4	M2.5*6mm		2.9 M4*26.5mm
1.5	M2.5*8mm		3.0 M4*40m
1.6	M2.5*10mm		3.1 M7*15mm
1.7	M3*6mm		N/7 TSHIIII
1.8	M3*8mm	0	3.2 M3*12mm
1.9	M3*6mm		3.3 M4*5mm
2.0	M3*8mm		3.4 M4*6mm
2.1	M3*10mm	0	3.5 M2 Nut
2.2	M3*12mm		3.6 M3 Nylon Nut
2.3	M3*16mm		3.7 M4 Nylon Nut
2.4	M3*17.8m	nm 🔘	3.8 M5 Nylon Nut



Shims and washers.

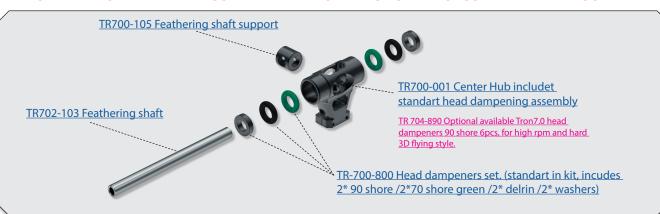


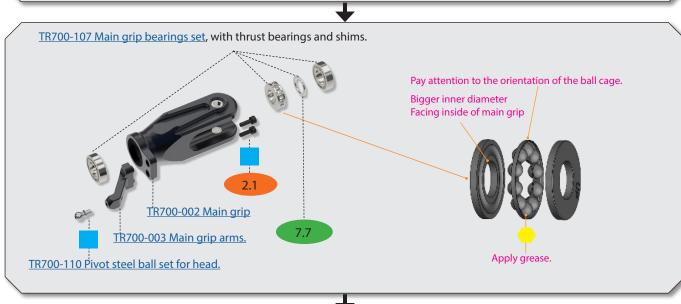


You will need: Loctite 243 = blue Grease = yellow

Head assembly

IMPORTAND NOTE: ALL PRE-ASSEMBLED PARTS NEEDS TO BE DISASSEMBLED AND LOCKTITED!

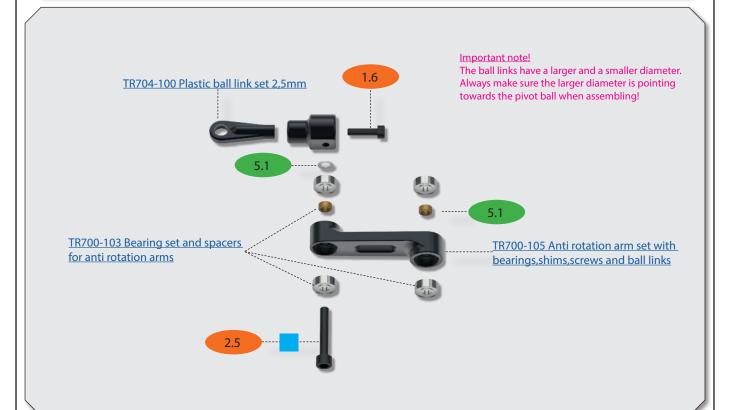








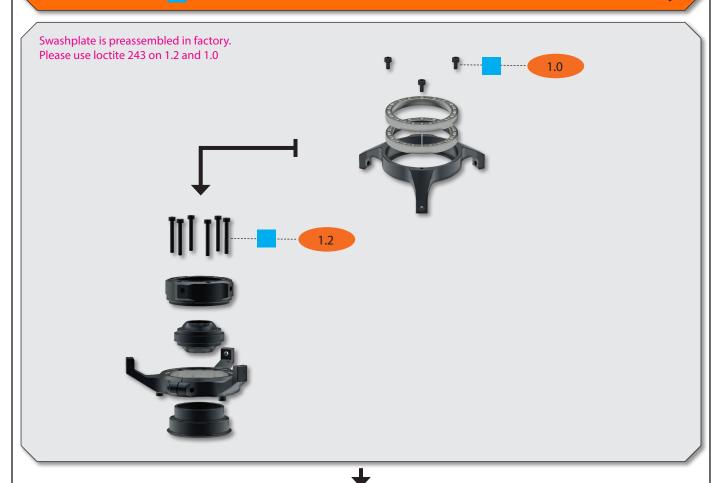
Head assembly

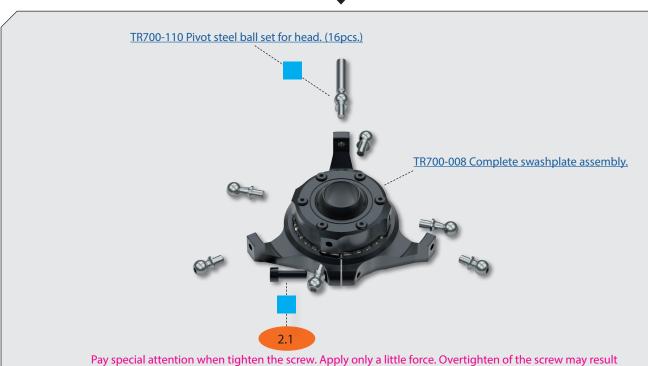






Head assembly

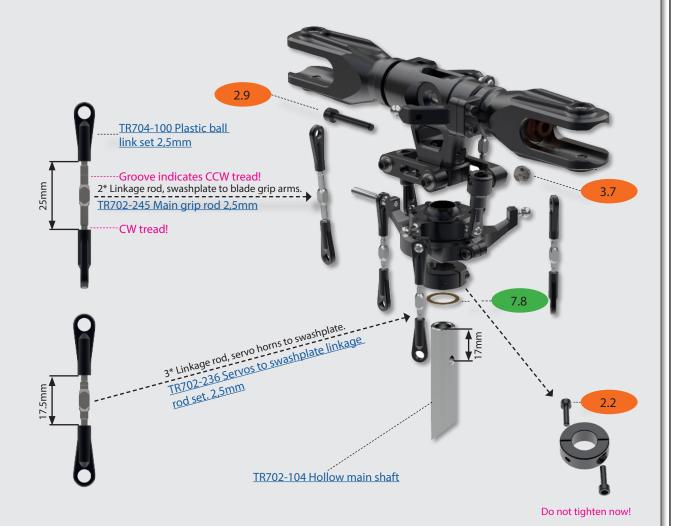




in swahsplate bearing damage.

Head assembly

- 1. Insert main shaft into center hub first.
- 2. Tighten screw 2.9
- 3. Tighten screw 2.6 left and right step by step (use loctite 248). Make sure the shim 5.2 do not fall off. (page 12)

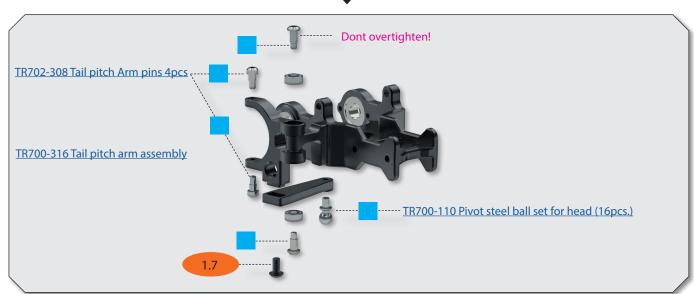


<u>Important note!</u>

The ball links have a larger and a smaller diameter. Always make sure the larger diameter is pointing towards the pivot ball when assembling!



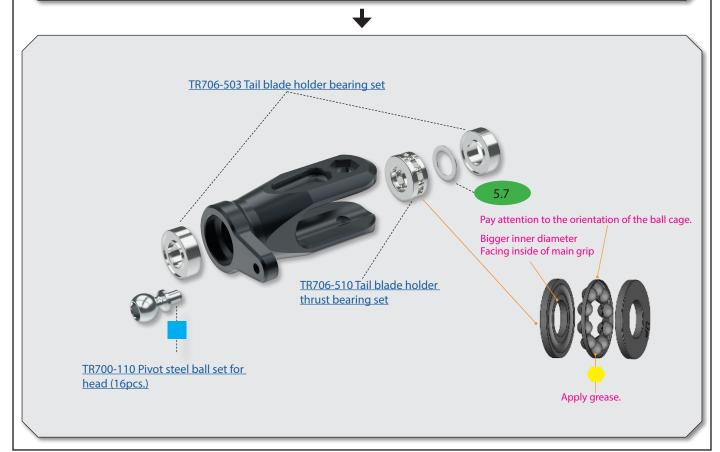






You will need: Loctite 243 = blue Grease = yellow

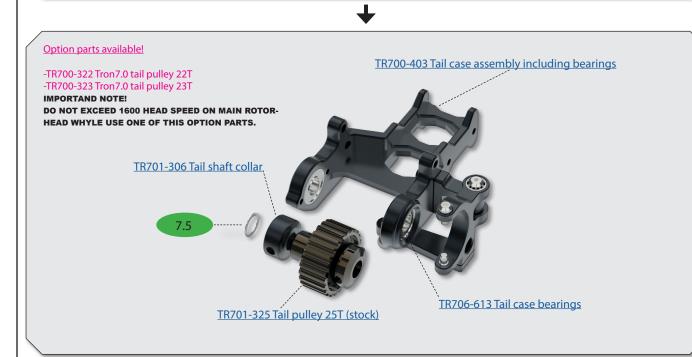




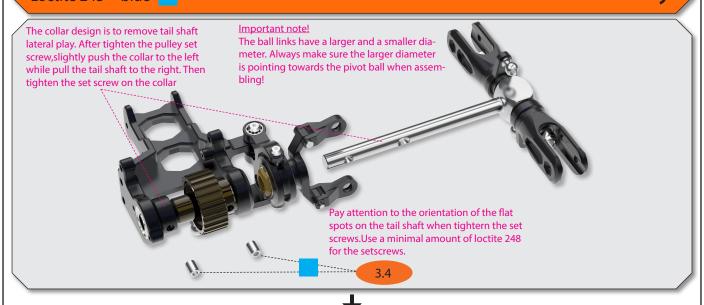




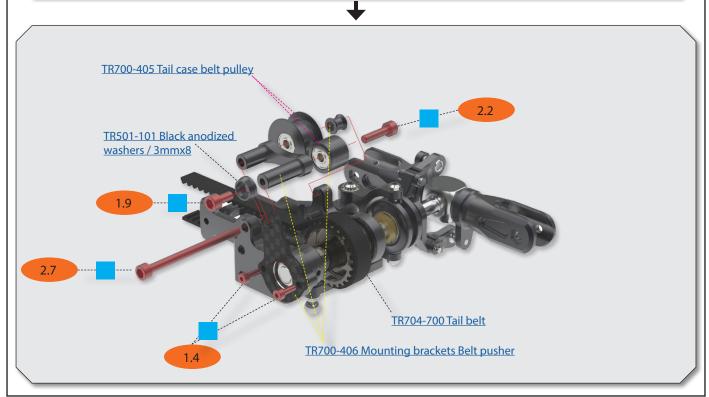








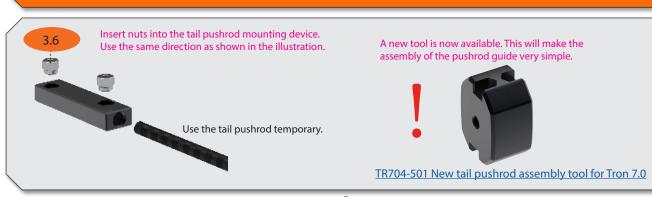




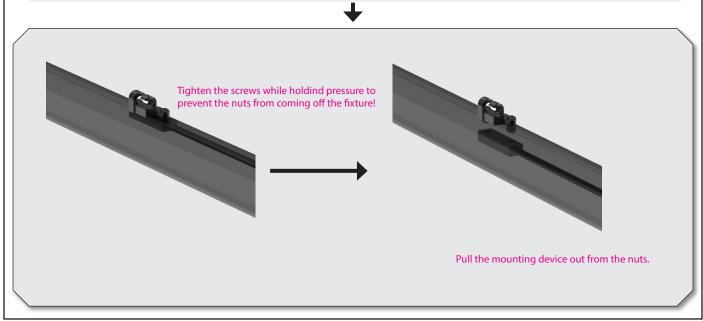


You will need:

A little bit of patience when assembling it for the first time









15mm

15mm on both sides. Use 2 component epoxy!

You will need: 2 component epoxy

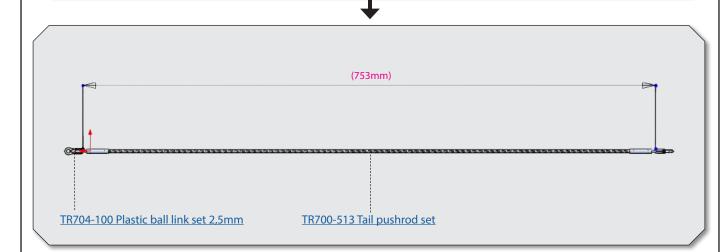
Tail assembly

-Pre assemble the threaded rod and the shell.
-Adjust the threaded rod to a length of 15mm. (same as shown in the illustration below
-Glue the tread into the tail push rod and the shell on the outside of the rod. Use 2 component epoxy!

please let it dry overnight to achieve 100% strength

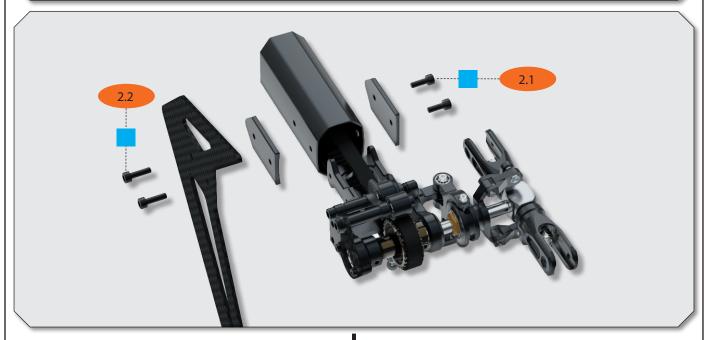
Apply 2 component epoxy on the outside of the carbon rod.

Apply 2 component epoxy inside the hole of the carbon rod to glue the treaded rod versus the carbon rod.





Tail assembly





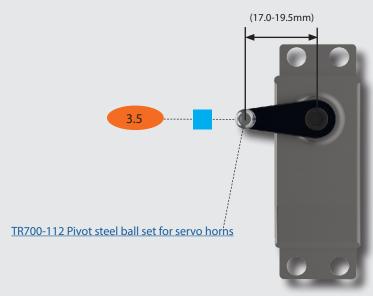
For best tail authority performance adjust center position of your FBL controller (tail servo) same as shown in the illustration (90*) degree.



Servos preparation

Cyclic servo arm lenght for Tron 7.0 (3* full size)

17.00-19.5mm, depending on the brand of the servos and the mounting position of the servos. Make sure that all 3 swashplate servos are mounted in the same way. Depending on the best possible geometry.







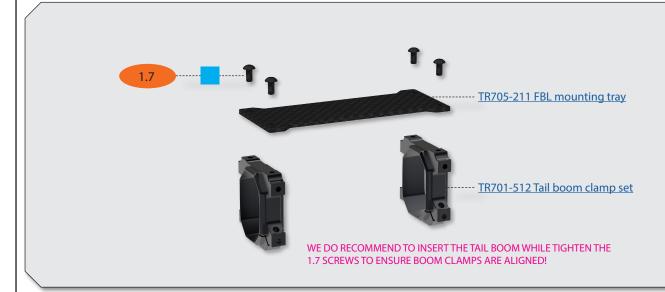
Battery tray





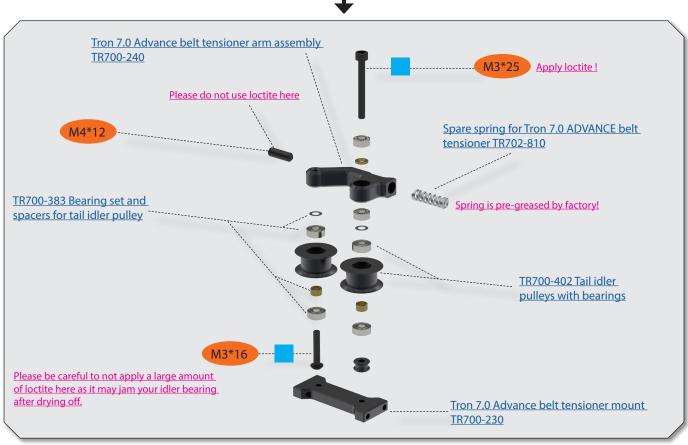




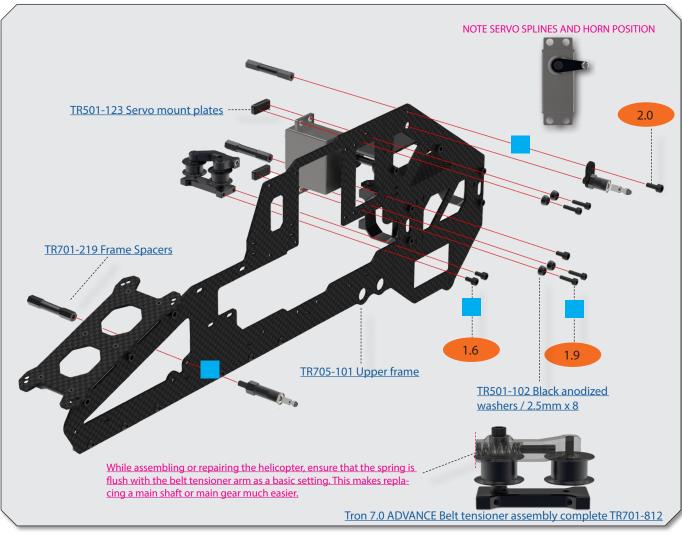


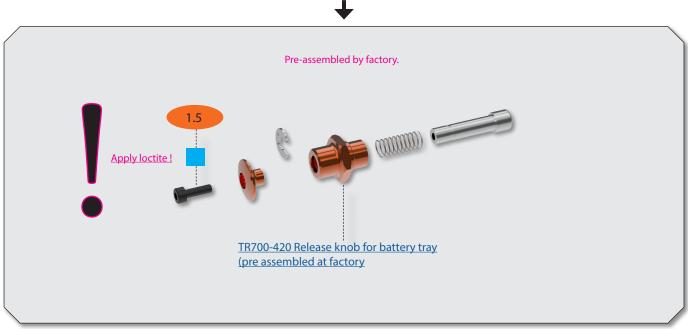




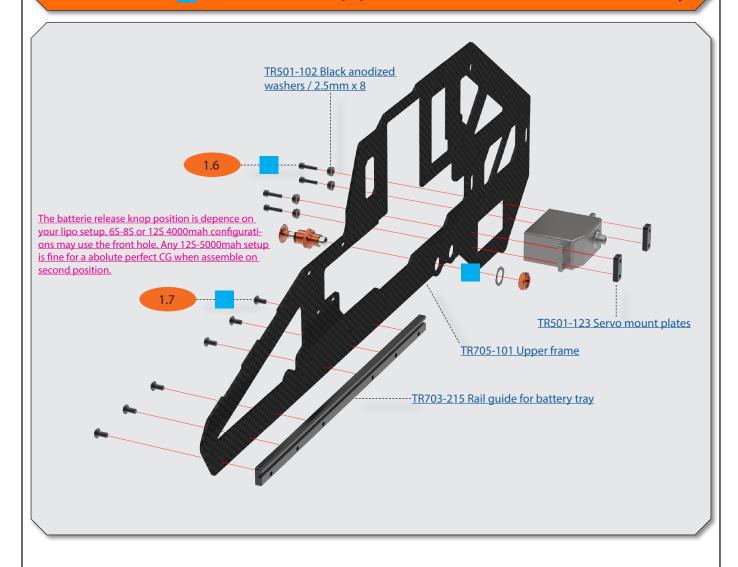












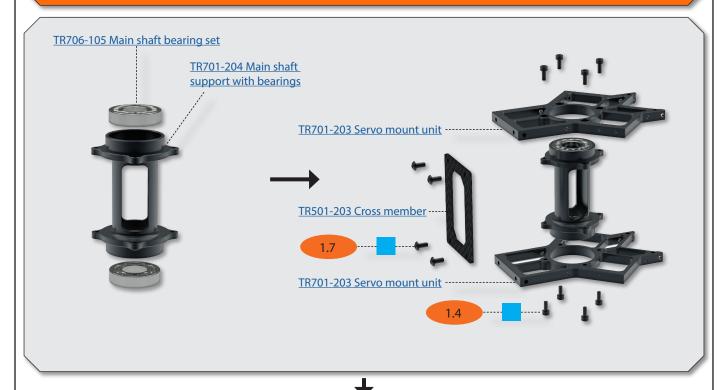


Motor mount and pinion





Servo frame and motor support

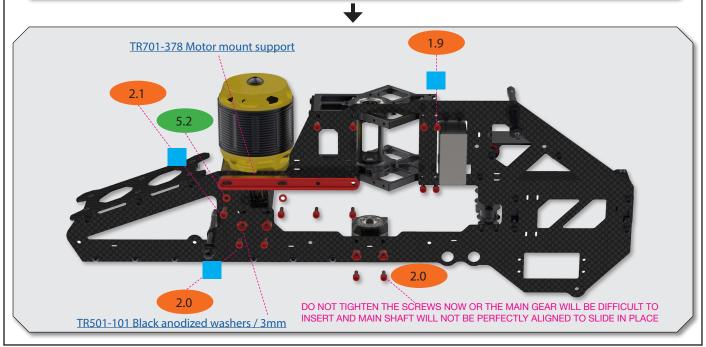


TR506-105 Main shaft bearing set-

When final assembling of the main gear, press shaft suport up versus the main gear assembling to remove up and down play. (page 37)



TR701-205 3rd bearing block



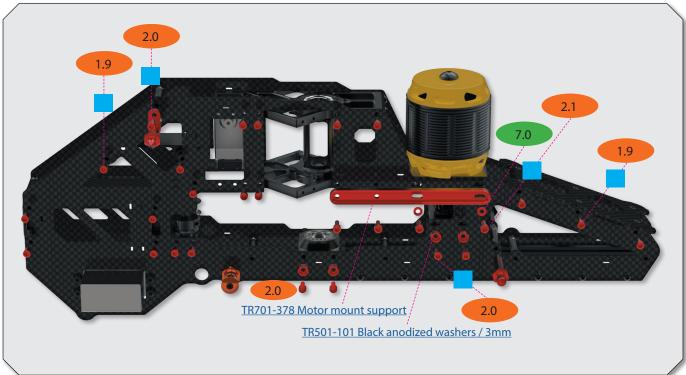


Upper and lower main frame assembly





Upper and lower main frame assembly

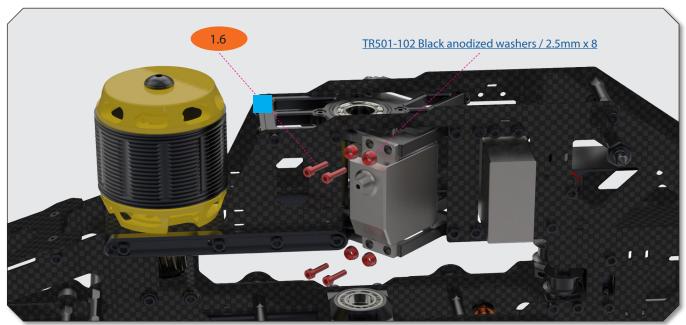






Landing gear and cyclic servos

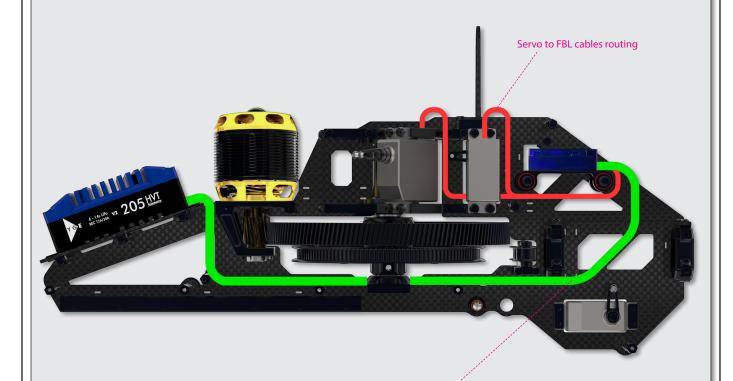






Tips Wiring

Additionally, you may want to use servo wire protection shrink tube to avoid cuffing or cutting on servo wires. Please make sure all edges on the frames which are in contact with wires are eased with sandpaper.

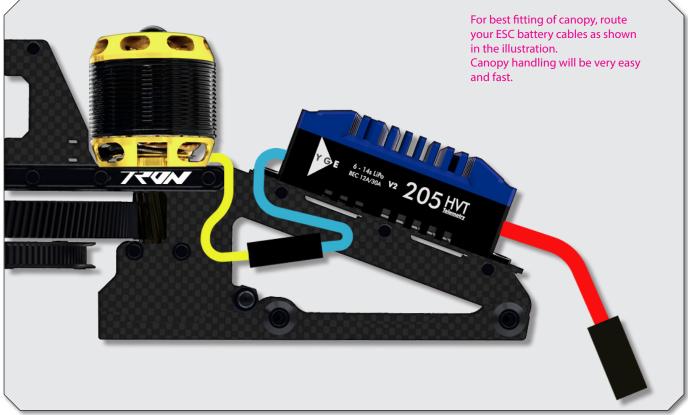


ESC to FBL cables routing



Tips Wiring

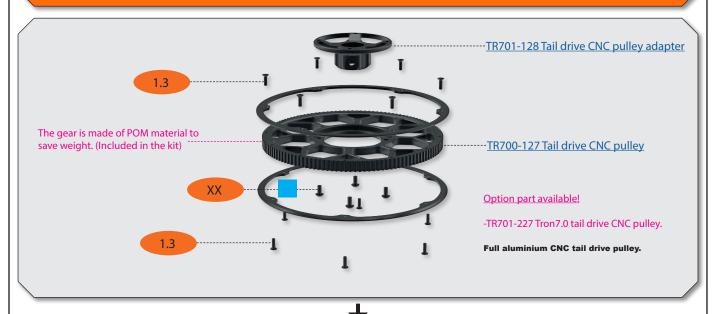






You will need: Loctite 243 = blue Grease = yellow

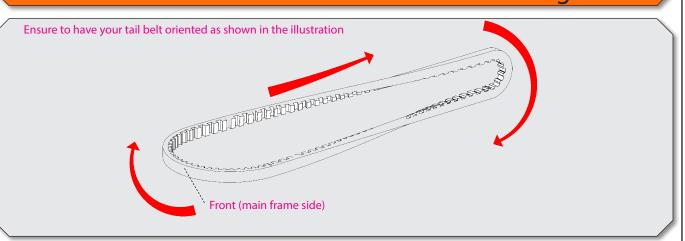
Main drive preparation

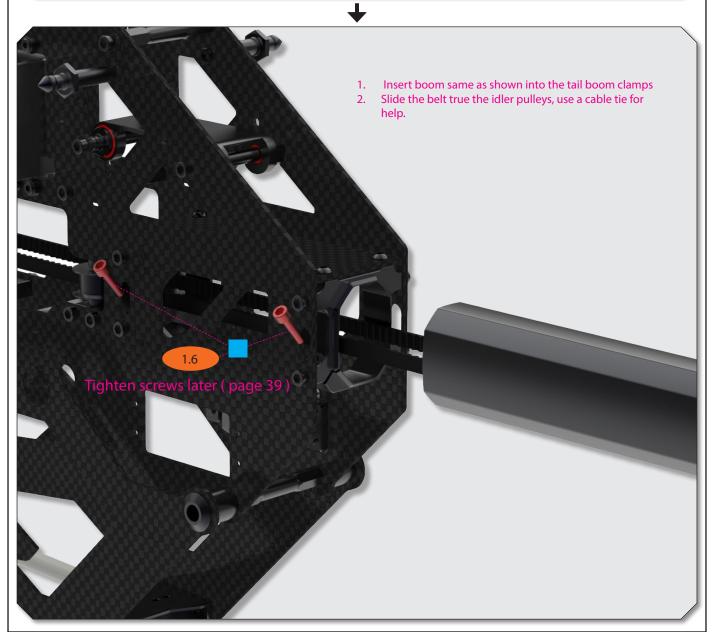






Tail boom and herringbone main gear alignment.







Head and main drive

- 1. Insert main gear assembly into frame while pulling tail belt over drive pulley
- 2. Insert rotor head assembly
- 3. Make sure your main shaft glide true the one way bearing sleeve and line up with the jesus bolt screw 2.9 and the lower main shaft bearing support.
- 4. Hold the lower main shaft bearing support versus the one way bearing assembly and tide up the screws.
- 5. Move down the main shaft collar to have zero up and down play on the rotor head assembly, then tighten screws equally.
- 6. Make sure to have an equal gap on the collar to achieve best holding results for the main shaft.



IMPORTAND NOTE!

Thanks to the flexible split design, which compresses under load, it detects and compensates for even the smallest vertical displacements. This way the main gear always will stay in the perfect position. In adition ,no vertical alignments or adjustments are required thanks to the motor Pinion's unique design.

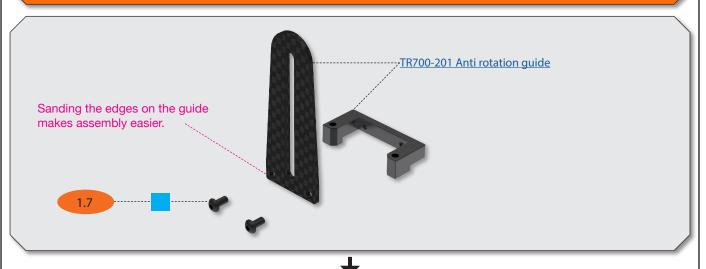
FOR MOTOR PINION VERSUS MAIN GEAR PLAY /GAP ADJUSTMENT PROCEED AS FOLLOWING:

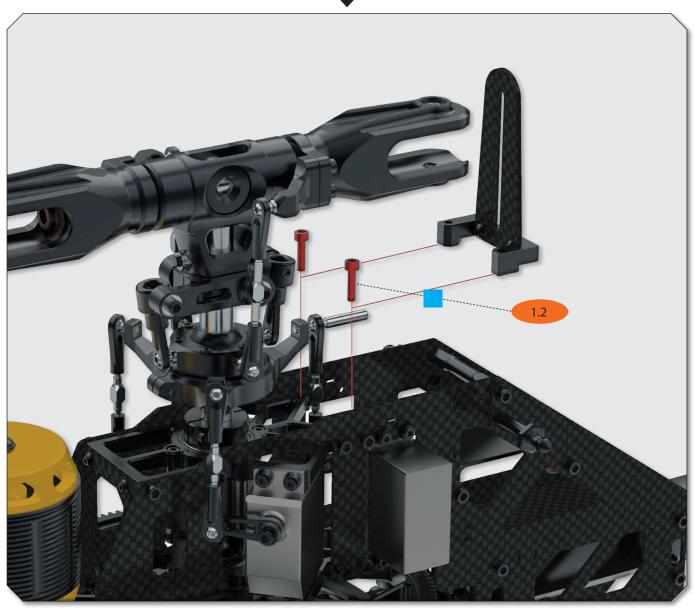
- Assemble all 4 screws to your motor mount but do not tighten them up.
- Carefully slide the motor mount versus the main gear until you have a contact.
- Carefully turn you main gear by hand without adding clearance. You should feel a smooth and free spinning of the main gear. No clearance is required.
- Carefully tighten the motor mount screws crosswise, use loctite.
- Check again: your main gear should rotate freely and smoothly without any play.





Anti rotation guide





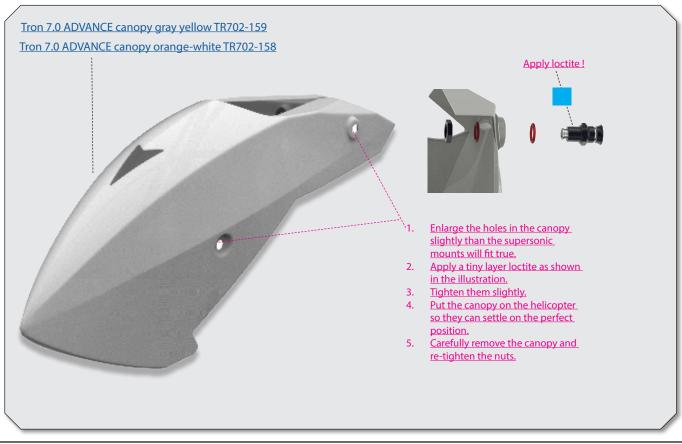


Tips

Belt tensioner and canopy

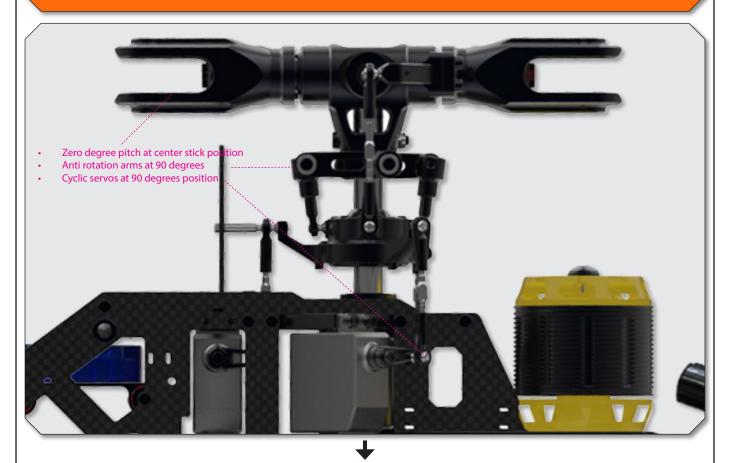


- Tension the tail belt as you normally would at room temperature
- 2. <u>Tighten the 2 boom clamp screws.</u>
- 3. Apply around 5-6 full turns on the set screw which will preload the spring now.
- Enjoy flying, no matter it's cold or hot or whatever without of readjusting your tail belt tension. Let him do the work:)





Final setup and pre-flight check



- 1. <u>Disconnect your Motor wires</u> from the ESC!
- 2. FBL controller should be to set to the mode where you can level your servo center position and, or swashplate level mode.
- 3. Fine tune your servo center position as precise as you can by the position of the servo horns. For finetuning use Sub trims in the FBL software.
- 4. Adjust your linkage from the servos to the swashplate as shown in the illustration. (90 degree)
- 5. Adjust your swashplate to Blade grip linkage to achieve 0 pitch at center stick position.
- 6. Continue setup as required in your FBL controller software.





Pre-flight check and gear ratios

Recommended head speed.

- 1. Make sure your battery ..., ... securely locked. Use 4 battery straps.
- 2. Inspect your blades for possible damage and if they are slightly tighten.
- 3. Inspect your linkages if they all in place and not have been popt off turing transport of your model.
- 4. Confirm that the FBL unit is correctly initialized.
- 5. Make sure your canopy is secured safely. (2 pins on backside are fine)
- 6. If you are a beginner, always seek advice by a expirianced pilot, specially for your first flight.

Flying styles	Head speed		
Beginner and sport flying.	1500-1900rpm.		
Advanced sport, 3D flying.	1900-2200rpm.		
Hardcore 3D flying.	2200-2400rpm.		

Main and tail rotor gear ratios.

Main gear	Pinion	Ratio	Tail drive	Tail	Ratio
151	15T	10.06	127T	23T	5.52
151	16T	9.43	127T	22T	5.77
151	17T	8.88			

INCLUDED IN KIT

Make sure to check your model on regular basis, do a preflight check every time you plan to fly your model. <u>Max. head speed for main rotor head must not exceed 2600 RPM!</u>
<u>IMPORTAND NOTE!</u>

DO NOT EXCEED 1600 HEAD SPEED ON MAIN ROTORHEAD WHEN USE 22T OR 23T TAIL PULLEY

Contact

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